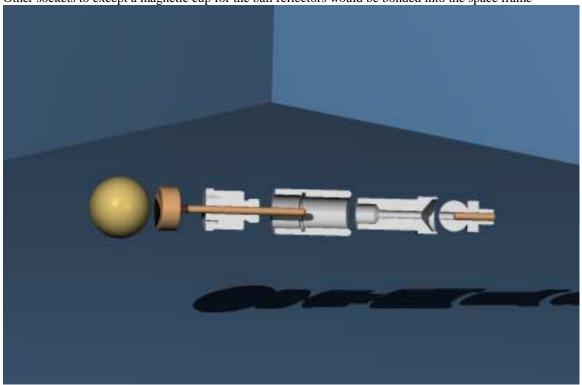
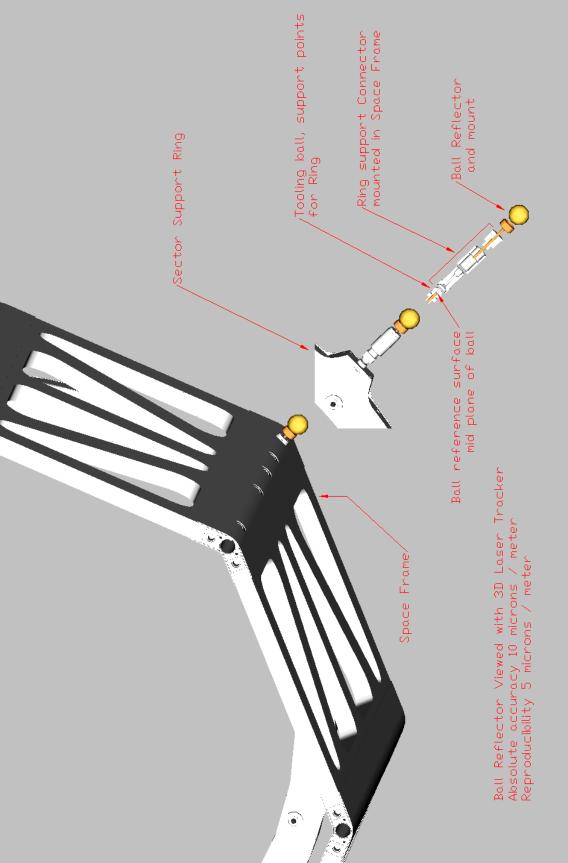
Atlas Pixal Survey

With detectors mounted on sectors and using mounting holes to construct datum measure all detector targets relative to datum on both sides.

With sectors mounted on sector support ring and using support balls for datum re-measure subset of targets relative support ball datum.

After sector support ring is mounted in space frame the position of ring support balls is transferred through the space frame by a probe with a magnetic cup at one end that supports a ball reflector. The probe runs down the axis of the support ball connector that is bonded into the space frame. By making two measurements one with the probe full in and another practically in the location of the ball is knowen. Other sockets to except a magnetic cup for the ball reflectors would be bonded into the space frame





Measuring principle of the 3D Laser Tracker LTD500

Basic Principle

The combination of horizontal and vertical angle measurements with distance measurements allows determining the 3D coordinates of a reflector within any tool or part coordinate system. Motors support fully automated measurements and a position detector guarantees high speed tracking capabilities.

Leica's Key Technology

While the angles are measured with high precision encoders, distances can be derived from Leica's patented absolute or interferometric distance measuring devices.

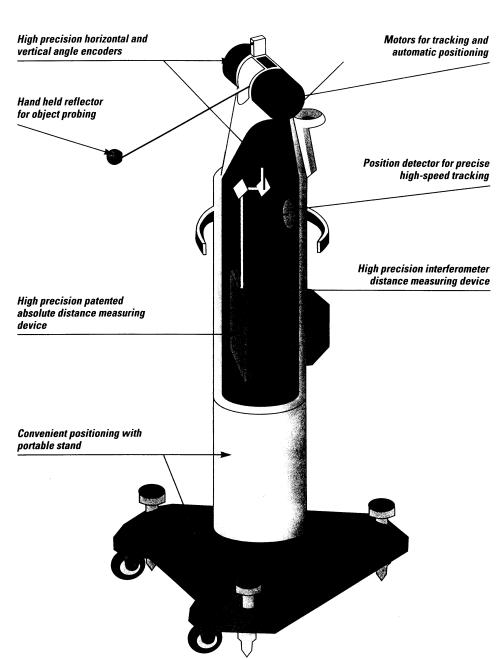
Laser Tracker LT(D) 500

The LT500 incorporates the interferometer technology for precise and fast tracking and scanning jobs.

The LTD500 with the additional absolute distance measuring device increases productivity, flexibility and automation.

Flexible positioning

The Laser Tracker can be mounted on Leica's portable stand or any other state of the art height adjustable device. In addition vertical positioning of the measurement head is possible.



Specifications

Tracking

Max. target speed

at right angles to the laser beam > 4.0 m/s in the direction of the laser beam > 6.0 m/s

Max. acceleration

in all directions Range of measurement

horizontal vertical

MALEN 120 COMS ± 235° ± 45° ~ 0-35 m (0-115')distance air path corner cube, Retroreflector cateve, solid glass corner cube

> 2 g

0.14"

1.26 um

± 5 ppm (µm/m)

Accuracy

Angle resolution 2 SIGMA Distance resolution Reproducibility of a coordinate*

Absolute accuracy of a coordinate*

± 10 ppm (µm/m) for non-moving target (static) $\pm 20-40 \text{ ppm (µm/m)}$ for moving target (dynamic)

Laser Interferometer

Principle of operation Single-beam interferometer

Class 2 Laser Product Wave length

Beam diameter (1/e2)

heterodyne < 0.3 mW/CW 633 nm (visible)

ca. 4.5 mm

Absolut Distance Meter (only LTD500)

Principle of operation light polarization modulation

Resolution 1 um

± 0.05 mm (0.002") Accuracy* 2-35 m (7-115')Measurement range < 0.5 mW/2 sec. Class 1 Laser Product

Wave length 780 nm (infrared) ca. 10 mm Beam diameter

The accuracy shown above (*) is stated as a 2 σ (sigma) value. In North America, it is customary to state accuracy as a 1 σ (sigma) value. In an approximation 1 σ values can be derived by deviding 2 σ values by two.

LTD500 is manufactured under the following US patents: Nr. 4714339 and Nr. 5530549. Other US and international patents pending.

Ambient Conditions

Working temperature (three ranges) Storage temperature Relative humidity

Air pressure/elevation operation

storage

+5°-+40° C +41°-+104° F -10°-+60° C +14°-+140° F 10-90% (non-condensing)

0-3000 m 0-10000 ft 0-7000 m 0-23000 ft

Dimensions and Weight

Sensor unit dimensions LT500/LTD500

transit axis height weight LT500

Controller

dimension

weight LTD500

weight

220 x 280 x 855 mm 8.7" x 11" x 33.7" 805 mm 31.7" 30.0 kg 66.1 lb

31.5 kg 69.0 lb 455 x 350 x 200 mm

17.9" x 13.8" x 7.9" 10.5 ka 23.1 lb

Recommended System Computer

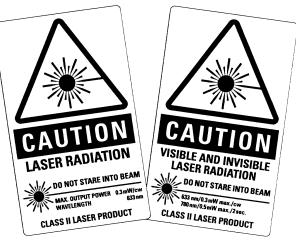
Personal Computer Operating system

Rate of measurement Real time output

Compag PentiumTM Windows® 95, 97, 98 or

NT4.0

up to 1000 points/sec. via parallel interface



LT 500

LTD 500